



JVL
intelligent motors

Troubleshooting guide for MIS and MAC

Instructions for solving common issues



1 Important User Information



Warning

The MAC series of products are used to control electrical and mechanical components of motion control systems. You should test your motion system for safety under all potential conditions. Failure to do so can result in damage to equipment and/or serious injury to personnel.

Please contact your nearest JVL representative in case of technical assistance. Your nearest contact can be found on our web site www.jvl.dk

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2 Revisions

Ver.	Changes	Date	Init
1.0	Original document	2021-10-06	AW
1.1	Partially rewrote and updated document. New template used.	2024-10-30	JLN



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Introduction

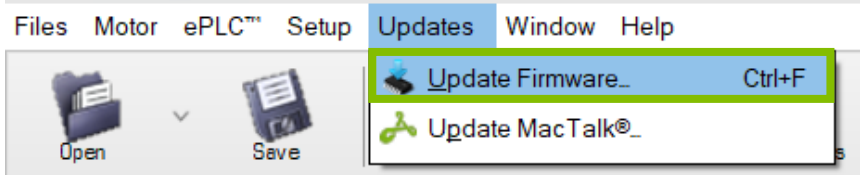
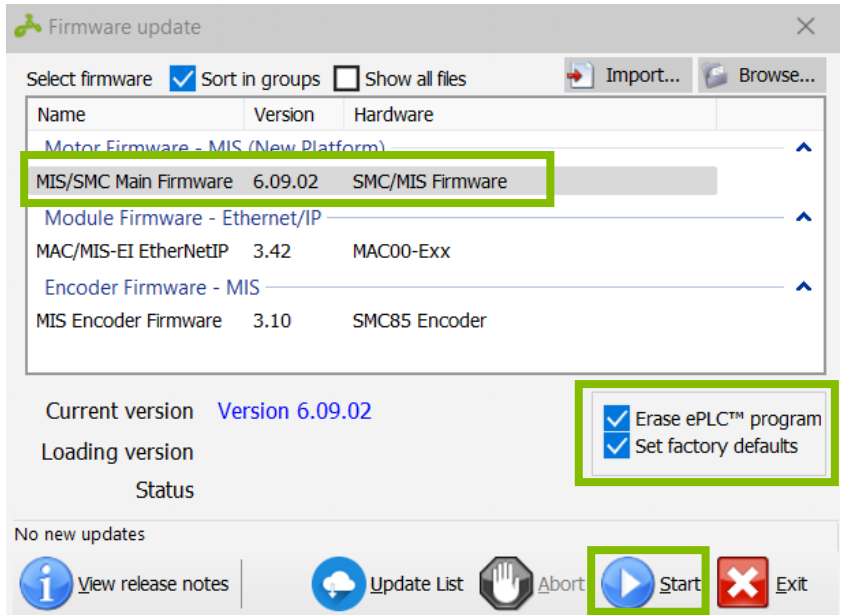
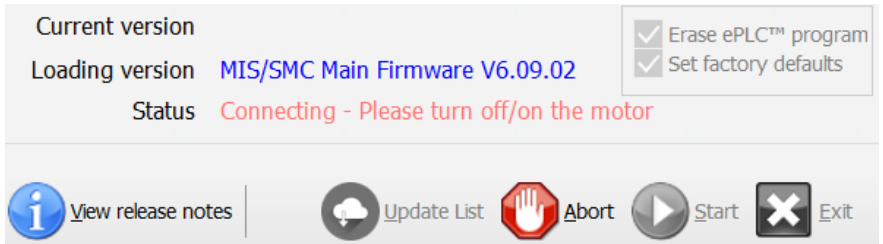
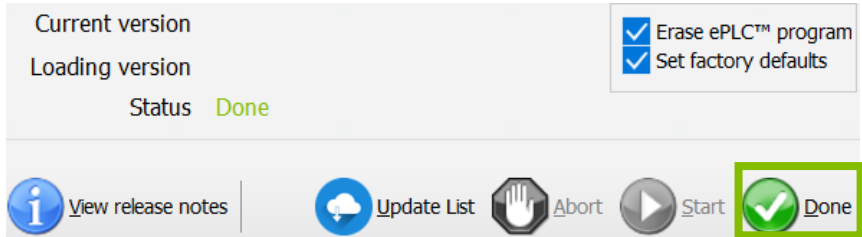
The following document is a guide to troubleshooting problems on MAC motor® Integrated Servo Motors and MIS ServoStep™ Integrated Stepper Motors. It contains step-by-step instructions to diagnosing and/or solving common issues one might encounter while using the motors.



4 Force updating firmware

Before performing this, please make sure that you are using serial communication.

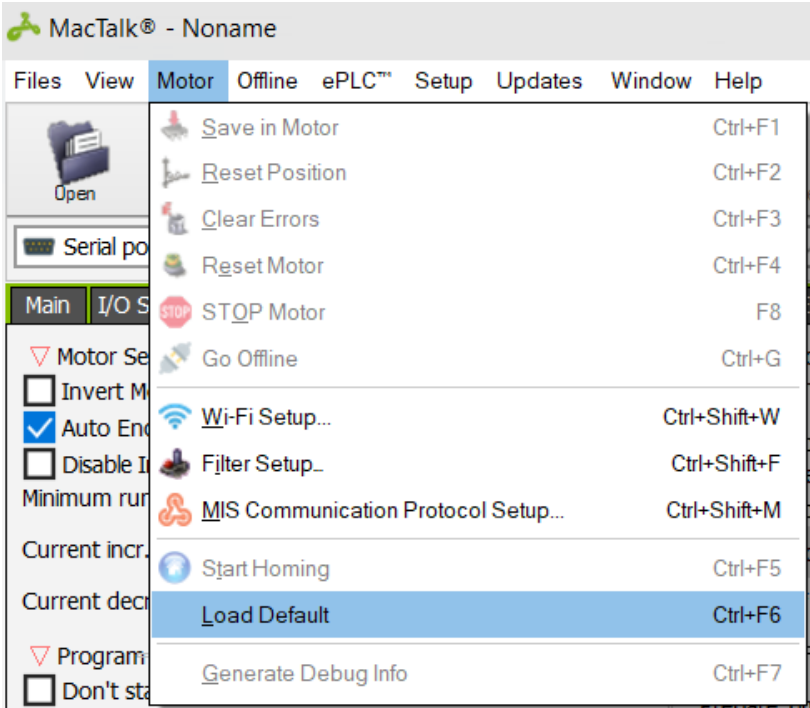
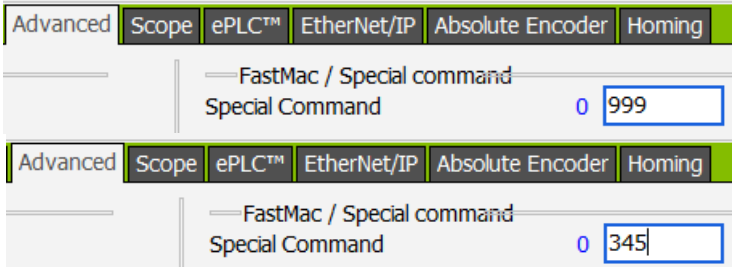
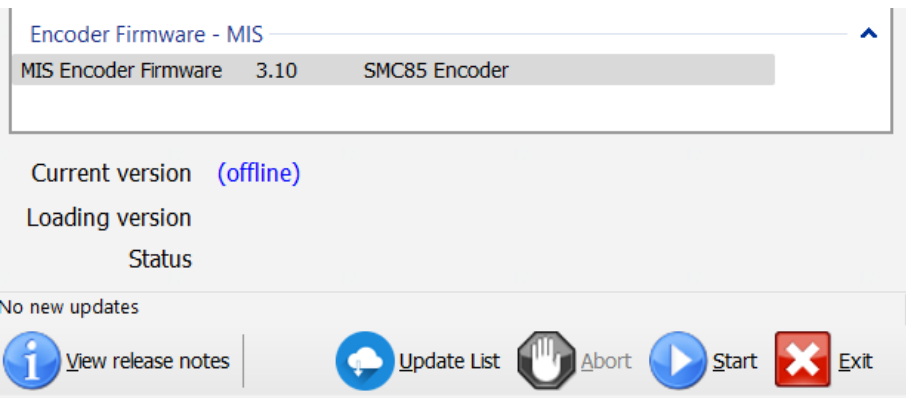
We recommend using our adapters: **RS485-USB-ATC-820**, **RS232-USB2.0-1** or **USB-RS232/485-OPTO**, as you might otherwise encounter issues.

Step	Text	Image
1	Without power (CVI/24 VDC control voltage), go to “Updates” – “Update firmware”	
2	Select the correct firmware for your motor type. Note: Check the motor model. If it is incorrect, you can check the “Show all files” option and choose the correct firmware for your motor.	
3	Once the pictured status message shows, turn on the 24 VDC supply.	
4	Once the update is complete, your motor will be back to default settings. Press “Done”	

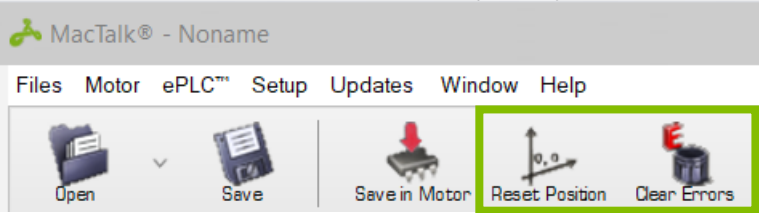
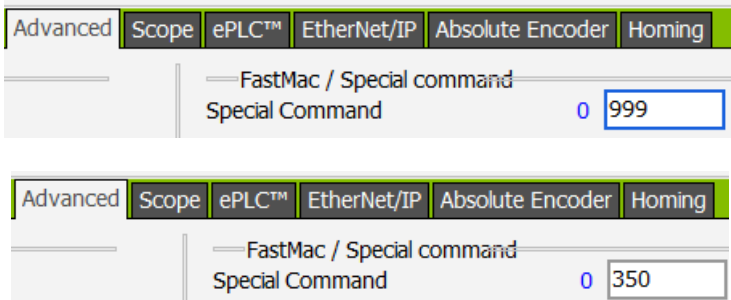


5 Restoring/updating encoder firmware

In the case that the encoder loses its firmware, or it needs to be updated as in sections 7 and 8, perform the following steps:

Step	Text	Image
1	Power on the motor and load default values in MacTalk (CTRL + F6).	
2	Issue command 999 and then 345. To verify that the command has worked, there should be no negative values in the P1/P2 registers.	
3	Update the encoder to the latest version.	



<p>4</p>	<p>After the update, the motor should display the following errors: Lost position, Encoder error.</p> <p>Click the “Reset position”, and “Clear errors”</p>	
<p>5</p>	<p>With no load connected to the motor, issue command 999 and then 350.</p> <p>Wait for the motor to perform the calibration. This may take up to three minutes.</p> <p>When register P1 reads 64 or the motor stops moving, the process is finished.</p>	<p>Any load must be removed before performing this step!</p> 

If the problem is still present, please contact JVL technical support.



6 Common connection issues

6.1 Power

The motors require Control Voltage (24 VDC) to communicate. Please make sure this is connected to the correct pins and include proper grounding.

On a MAC motor: If there are LEDs on your module, please make sure these are illuminated.

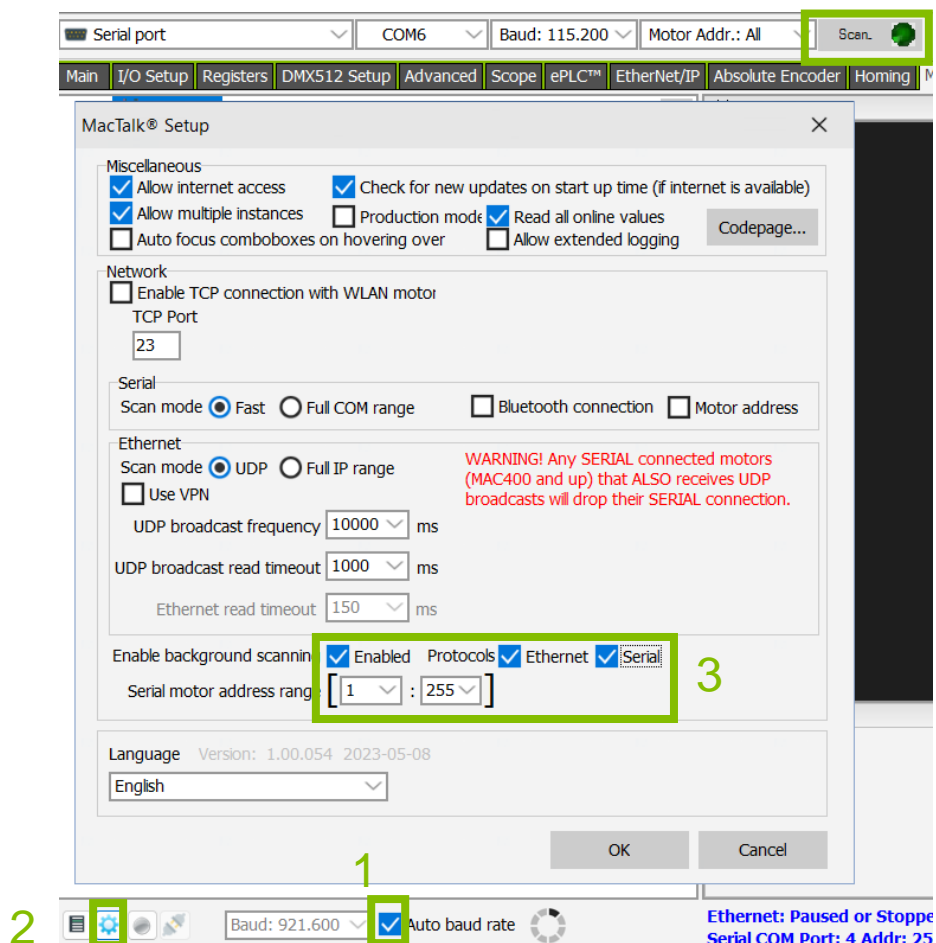
On a MIS motor: The LEDs should illuminate when power is attached, L3 should stay turned on.

6.2 Communication

Please make sure that you have a functioning USB-RS485 (MIS) or USB-RS232 (MAC) converter. Unfortunately, we have extensive experience where issues arise, such as firmware updates failing, due to the serial adapter.

We sell converters that we have personally certified as working for all communications tasks. The models that we can provide are **RS485-USB-ATC-820**, **RS232-USB2.0-1** and **USB-RS232/485-OPTO**. Additionally, please make sure that you are using the correct communication cable; RSxxx-M12-1-5-xx.

Ensure that no other programs on the PC is trying to use the chosen COM port. Open MacTalk and choose the search radar icon in the top right corner [1]. Select the auto baud rate checkbox. If this does not work, click the cog icon [2], and select the widest address range [3]. Then click OK.



If the motor still does not connect, select every baud rate one by one in the “Baud: “ dropdown menu next to the scan button. If this does not work, follow the instructions in section 4: *Force updating firmware*.



7 MIS: Encoder Com Error

Does the encoder firmware version read as “0.00”?

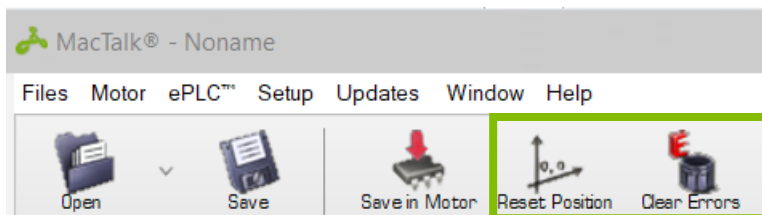
Yes: Update the H3/H4 encoder firmware by following the instructions in section 5: *Restoring/updating encoder firmware*.

No: Contact technical support.

To verify that the H3 calibration data is saved, issue command 355 and check register P1. If P1=1, OK

8 MIS: Encoder Lost Position

Click “Reset Position” and “Clear Errors”



If the error is cleared:

Use any active mode to make the motor move for a while. Verify that the error does not return. Disconnect the power and turn the shaft by hand for a couple of revolutions. Wait five minutes. Connect the power again. If the error is still gone, the motor should function normally again.

If the error is still present:

Update the encoder firmware and perform the automated calibration as in section 5: *Restoring/updating encoder firmware*. Then, perform the steps from “If the error is cleared” above.

If the problem is still present, please contact JVL technical support.



9 MIS: Encoder Counting Error

Usually, this issue is caused by a hardware issue. It is normally unrecoverable. In the manual, it is known as “Encoder Reed Error”:

Error message 'Encoder Reed error'

Message no. / Message	9 / 'Encoder Reed error'
Type / Motor action	Unrecoverable error / Motor is set in Passive mode.
Error condition	<ul style="list-style-type: none"> • The absolute multi turn encoder (H3/H4) has detected a wrong sequence in the positioning algorithm. • This error also occurs after firmware update.
Possible cause of this error	<ul style="list-style-type: none"> • This can be caused by a mechanical shock on the shaft or an external magnetic field. • Because the encoder has been reset during a firmware update.
Solutions to avoid error	<ul style="list-style-type: none"> • Do not place the motor inside a strong magnetic field. • Do not expose the shaft or the motor for mechanical shocks.
How to return to normal operation	<ul style="list-style-type: none"> • Reset the position (special command 354 in register 24), clear the error bit(s) in register 35 or cycle the power.
Error bit / Firmware name	Bit 9

In addition to the solutions outlined above:

- Check the grounding and ensure that all cables are properly shielded.
- Consider mounting a direct wire from the motor chassis to the machine it is used in.

Does the error occur at any time, or only when running at high speeds (over 500 RPM)?

At all times: Ensure that there is no mechanical stress put on the shaft; excess pulling or pushing can cause the issue to occur.

Only at +500 RPM: The encoder needs to be serviced.

If none of these suggestions help, contact JVL technical support.

10 Closed Loop Error

Only valid for MIS/SMC

The H2 encoder needs to be calibrated, please follow the instructions in the link below:

http://www.jvl.dk/files/me/mis_cl_error_guide.pdf

11 Ethernet module not visible or “Internal error”

In the case a there is an issue in updating the firmware, the communication between the ethernet module and the motor can become corrupted.

- Update the module firmware.

If the correct module is not shown, press “Show all files” in the firmware update menu and select the proper firmware. If this does not work, force a firmware update by using the instructions in section **Error!**

Reference source not found.. Force updating firmware.



12 Low bus voltage

MIS/SMC

Is the correct bus voltage (same as supply) shown in "Bus Voltage (P+)" register 97?

- Yes: Clear error register 35 and status register 36.
- No: Are both CVI and P+ connected to the power source?
 - Yes: Replace unit or contact JVL technical support.
 - No: The unit needs both CVI and P+ to function

MAC with AC supply

Is the correct bus voltage ($V_{AC} \cdot \sqrt{2}$) shown in "Bus Voltage" register 198?

- Yes: Clear error register 35 and status register 36.
- No: Is the Main Power Connector, connected to the power source?
 - Yes: Replace unit or contact JVL technical support.
 - No: The motor needs AC supply to function.

MAC with DC supply

Is correct bus voltage (same as supply) shown in "Bus Voltage" register 198?

- Yes: Clear error register 35 and status register 36.
- No: Is the Main Power Connector, connected to the power source?
 - Yes: Replace unit or contact JVL technical support.
 - No: The motor needs DC supply at the Main Power Connector.

Old MiniMAC

Is correct supply voltage (same as supply) shown in "Supply Voltage" register 151?

- Yes: Clear error register 35 and status register 36.
- No: Is the main connected to the power source?
 - Yes: Replace unit or contact JVL technical support.
 - No: The motor needs DC supply to function.

Applicable to all

Before replacing the unit or contacting JVL support, please make sure the external fuse is intact by unplugging the power cable and measuring the voltage from the connector.